
SUPAC: Manufacturing Equipment Addendum

Guidance for Industry

**U.S. Department of Health and Human Services
Food and Drug Administration
Center for Drug Evaluation and Research (CDER)**

**December 2014
Pharmaceutical Quality/CMC**

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TABLE OF CONTENTS

I.	INTRODUCTION.....	1
II.	BACKGROUND	2
III.	DISCUSSION	2
IV.	SUPAC IR/MR INFORMATION.....	3
A.	Particle Size Reduction/Separation	3
1.	<i>Definitions.....</i>	<i>3</i>
2.	<i>Equipment Classifications</i>	<i>4</i>
B.	Blending and Mixing.....	6
1.	<i>Definitions.....</i>	<i>6</i>
2.	<i>Equipment Classifications</i>	<i>6</i>
C.	Granulation	7
1.	<i>Definitions.....</i>	<i>7</i>
2.	<i>Equipment Classification.....</i>	<i>9</i>
D.	Drying	11
1.	<i>Definitions</i>	<i>11</i>
2.	<i>Equipment Classifications</i>	<i>13</i>
E.	Unit Dosing	14
1.	<i>Definitions</i>	<i>14</i>
2.	<i>Equipment Classifications</i>	<i>15</i>
F.	Soft Gelatin Capsule	16
1.	<i>Definitions</i>	<i>16</i>
2.	<i>Equipment Classifications</i>	<i>18</i>
G.	Coating/Printing/Drilling	19
1.	<i>Definitions</i>	<i>19</i>
2.	<i>Equipment Classification.....</i>	<i>22</i>
V.	SUPAC-SS INFORMATION.....	24
A.	Particle Size Reduction/Separation	24
B.	Mixing	24
1.	<i>Definitions.....</i>	<i>24</i>
2.	<i>Equipment Classification.....</i>	<i>25</i>
C.	Emulsification.....	25
1.	<i>Definitions.....</i>	<i>25</i>

Contains Nonbinding Recommendations

2. <i>Equipment Classification</i>	26
D. Deaeration	26
1. <i>Definitions</i>	26
2. <i>Equipment Classification</i>	27
E. Transfer	27
1. <i>Definition</i>	27
2. <i>Equipment Classification</i>	27
F. Packaging	28
1. <i>Definitions</i>	28
2. <i>Equipment Classification</i>	29

1 **Guidance for Industry¹**
2 **SUPAC: Manufacturing Equipment Addendum**
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4
5 This guidance represents the Food and Drug Administration's (FDA's or Agency's) current thinking on
6 this topic. It does not create or confer any rights for or on any person and does not operate to bind FDA
7 or the public. You can use an alternative approach if the approach satisfies the requirements of the
8 applicable statutes and regulations. If you want to discuss an alternative approach, contact the FDA staff
9 responsible for implementing this guidance using the contact information on the title page of this
10 guidance.
11

12
13
14
15 **I. INTRODUCTION**
16

17 This guidance combines and supersedes the following scale-up and post-approval changes
18 (SUPAC) guidances for industry: (1) *SUPAC-IR/MR: Immediate Release and Modified*
19 *Release Solid Oral Dosage Forms, Manufacturing Equipment Addendum*, and (2) *SUPAC-SS*
20 *Nonsterile Semisolid Dosage Forms, Manufacturing Equipment Addendum*.² It removes the lists
21 of manufacturing equipment that were in both guidances and clarifies the types of processes being
22 referenced.
23

24 A draft guidance, *SUPAC: Manufacturing Equipment Addendum*, was published on April 1, 2013.
25 Comments were received and changes were made to address those comments.
26

27 This SUPAC addendum should be used in conjunction with the following SUPAC guidances for
28 industry:³ (1) *Immediate Release Solid Oral Dosage Forms — Scale-Up and Post-Approval*
29 *Changes: Chemistry, Manufacturing and Controls, In Vitro Dissolution Testing, and In Vivo*
30 *Bioequivalence Documentation*, (2) *SUPAC-MR: Modified Release Solid Oral Dosage Forms*
31 *Scale-Up and Post-Approval Changes: Chemistry, Manufacturing and Controls; In Vitro*
32 *Dissolution Testing and In Vivo Bioequivalence Documentation*, and (3) *SUPAC-SS: Nonsterile*
33 *Semisolid Dosage Forms, Scale-Up and Post Approval Changes: Chemistry Manufacturing and*
34 *Controls; In Vitro Release Testing and In Vivo Bioequivalence Documentation*.⁴
35

36 The SUPAC guidances define: (1) levels of chemistry, manufacturing, and control change; (2)
37 recommended chemistry, manufacturing, and controls tests for each level of change; (3)
38 recommended in vitro dissolution and release tests and/or in vivo bioequivalence tests for each

¹ This guidance has been prepared by the Office of Pharmaceutical Science in the Center for Drug Evaluation and Research (CDER) at the Food and Drug Administration.

² For this guidance only, the new document that is a combination of these two guidances will be referred to as the *SUPAC addendum*.

³ We update guidances periodically. To make sure you have the most recent version of a guidance, check the FDA Drugs guidance Web page at

<http://www.fda.gov/Drugs/GuidanceComplianceRegulatoryInformation/Guidances/default.htm>.

⁴ For this guidance only, this collective group of guidances will be referred to as *SUPAC guidances*.

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39 level of change; and (4) recommended documentation that should support the change for new
40 drug applications and abbreviated new drug applications.

41
42 This SUPAC addendum, together with the SUPAC guidances, is intended to help you, the
43 manufacturer, determine the documentation you should submit to FDA regarding manufacturing
44 equipment changes.

45
46 FDA's guidance documents, including this guidance, do not establish legally enforceable
47 responsibilities. Instead, guidances describe the Agency's current thinking on a topic and should
48 be viewed only as recommendations, unless specific regulatory or statutory requirements are
49 cited. The use of the word *should* in Agency guidances means that something is suggested or
50 recommended, but not required.

51 52 **II. BACKGROUND**

53
54 When the SUPAC equipment addenda were published with tables referencing specific
55 equipment, the tables were misinterpreted as equipment required by FDA. FDA recognizes
56 that scientific innovation and technology advancement are commonplace and play a significant
57 role in pharmaceutical development, manufacturing, and quality assurance, and we are
58 concerned that such a misunderstanding could discourage advancements in manufacturing
59 technologies. Therefore, this revised SUPAC addendum contains general information on
60 SUPAC equipment and no longer includes tables referencing specific equipment. This
61 guidance also includes changes to clarify the types of processes being referenced.

62 63 **III. DISCUSSION**

64
65 The information in this guidance is presented in broad categories of unit operation. For
66 immediate or modified release solid oral dosage forms, broad categories include blending and
67 mixing, drying, particle size reduction/separation, granulation, unit dosage, coating and printing,
68 and soft gelatin capsule encapsulation. For nonsterile semisolid dosage forms, broad categories
69 include particle size reduction and/or separation, mixing, emulsification, deaeration, transfer, and
70 packaging. Definitions and classifications are provided. For each operation, equipment is
71 categorized by class (operating principle) and subclass (design characteristic). Examples of types
72 of equipment, but not specific brand information, are given within the subclasses.

73
74 When assessing manufacturing equipment changes from one class to another or from one
75 subclass to another, you can follow a risk-based approach that includes a rationale and complies
76 with the regulations, including the CGMP regulations.^{5, 6} We also recommend addressing the
77 impact on the product quality attributes of equipment variations (via process parameters) when
78 designing and developing the manufacturing process.⁷

79

⁵ 21 CFR 314.70.

⁶ 21 CFR 210-211.

⁷ L. X. Yu, G. Amidon, M. A. Khan, S. W. Hoag, J. Polli, G. K. Raju, and J. Woodcock, Understanding Pharmaceutical Quality by Design. The AAPS Journal. March 2014.

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80 When making equipment changes, you will need to determine the filing requirement.⁸ The
81 SUPAC guidances provide information on how to do so. FDA will assess the changes based on
82 the types of equipment changes being considered. If you choose an approach that exceeds the
83 SUPAC guidances and addendum, FDA will assess the changes provided they are supported by
84 a suitable risk-based assessment.
85

86 At the time of the equipment change, you should have available the scientific data and rationale
87 used to determine the type of change and documentation required. This information is subject to
88 FDA review at its discretion.
89

90 **IV. SUPAC IR/MR INFORMATION**

91

92 **A. Particle Size Reduction/Separation**

93

94 *1. Definitions*

95

96 *a. Unit Operations*

97

98 *i. Particle Size Reduction:* The mechanical process of breaking particles into
99 smaller pieces via one or more particle size reduction mechanisms. The
100 mechanical process used generally is referred to as milling.

101

102 *a. Particle* – Refers to either a discrete particle or a grouping of particles,
103 generally known as an agglomerate.

104

105 *b. Particle Size Reduction Mechanisms*

106

107 *• Impact* - Particle size reduction by applying an
108 instantaneous force perpendicular to the
109 particle/agglomerate surface. The force can result from
110 particle-to-particle or particle-to-mill surface collision.

111

112 *• Attrition* - Particle size reduction by applying a force in a
113 direction parallel to the particle surface.

114

115 *• Compression* - Particle size reduction by applying a force
116 slowly (as compared to Impact) to the particle surface in a
117 direction toward the center of the particle.

118

119 *• Cutting* - Particle size reduction by applying a
120 shearing force to a material.

121

122 *ii. Particle Separation:* Particle size classification according to particle size
123 alone.

124

⁸ 21 CFR 314.70.

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- 125 b. Operating Principles
126
127 i. Fluid Energy Milling
128
129 Particles are reduced in size as a result of high-speed particle-to-particle
130 impact and/or attrition; also known as micronizing.
131
132 ii. Impact Milling
133
134 Particles are reduced in size by high-speed mechanical impact or impact
135 with other particles; also known as milling, pulverizing, or comminuting.
136
137 iii. Cutting
138
139 Particles are reduced in size by mechanical shearing.
140
141 iv. Compression Milling
142
143 Particles are reduced in size by compression stress and shear between
144 two surfaces.
145
146 v. Screening
147
148 Particles are reduced in size by mechanically induced attrition through a
149 screen. This process commonly is referred to as milling or
150 deagglomeration.
151
152 vi. Tumble Milling
153
154 Particles are reduced in size by attrition utilizing grinding media.
155
156 vii. Separating
157
158 Particles are segregated based upon particle size alone and without any
159 significant particle size reduction. This process commonly is referred to as
160 screening or bolting.

2. *Equipment Classifications*

- 162 a. Fluid Energy Mills
163
164 Fluid energy mill subclasses have no moving parts and primarily are distinguished
165 from one another by the configuration and/or shape of their chambers, nozzles,
166 and classifiers.
167
168
169
170 • Tangential Jet
171 • Loop/Oval

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- 172
- Opposed Jet
- 173
- Opposed Jet with Dynamic Classifier
- 174
- Fluidized Bed
- 175
- Fixed Target
- 176
- Moving Target
- 177
- High Pressure Homogenizer
- 178
- 179 b. Impact Mills
- 180
- 181 Impact mill subclasses primarily are distinguished from one another by the
- 182 configuration of the grinding heads, chamber grinding liners (if any), and
- 183 classifiers.
- 184
- Hammer Air Swept
 - Hammer Conventional
 - Pin/Disc
 - Cage
- 185
- 186
- 187
- 188
- 189
- 190 c. Cutting Mills
- 191
- 192 Although cutting mills may differ from one another in whether the knives are
- 193 movable or fixed and in the classifier configuration, no cutting mill subclasses
- 194 have been identified.
- 195
- 196 d. Compression Mills
- 197
- 198 Although compression mills may differ from one another in whether one or both
- 199 surfaces are moving, no compression mill subclasses have been identified.
- 200
- 201 e. Screening Mills
- 202
- 203 Screening mill subclasses primarily are distinguished from one another by the
- 204 rotating element.
- 205
- Rotating Impeller
 - Rotating Screen
 - Oscillating Bar
- 206
- 207
- 208
- 209
- 210 f. Tumbling Mills
- 211
- 212 Tumbling mill subclasses primarily are distinguished from one another by the
- 213 grinding media used and by whether the mill is vibrated.
- 214
- Ball Media
 - Rod Media
 - Vibrating
- 215
- 216
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g. Separators

Separator subclasses primarily are distinguished from one another by the mechanical means used to induce particle movement.

- Vibratory/Shaker
- Centrifugal

B. Blending and Mixing

1. Definitions

a. Unit Operations

Blending and Mixing: The reorientation of particles relative to one another in order to achieve uniformity.

b. Operating Principles

i. Diffusion Blending (Tumble)

Particles are reoriented in relation to one another when they are placed in random motion and interparticular friction is reduced as the result of bed expansion (usually within a rotating container); also known as tumble blending.

ii. Convection Mixing

Particles are reoriented in relation to one another as a result of mechanical movement; also known as paddle or plow mixing.

iii. Pneumatic Mixing

Particles are reoriented in relation to one another as a result of the expansion of a powder bed by gas.

2. Equipment Classifications

a. Diffusion Mixers (Tumble)

Diffusion mixer subclasses primarily are distinguished by geometric shape and the positioning of the axis of rotation.

- V-blenders
- Double Cone Blenders

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- 265 • Slant Cone Blenders
- 266 • Cube Blenders
- 267 • Bin Blenders
- 268 • Horizontal/Vertical/Drum Blenders
- 269 • Static Continuous Blenders
- 270 • Dynamic Continuous Blenders

b. Convection Mixers

271
272
273 Convection blender subclasses primarily are distinguished by vessel shape and
274 impeller geometry.
275

- 276 • Ribbon Blenders
- 277 • Orbiting Screw Blenders
- 278 • Planetary Blenders
- 279 • Forberg Blenders
- 280 • Horizontal Double Arm Blenders
- 281 • Horizontal High Intensity Mixers
- 282 • Vertical High Intensity Mixers
- 283 • Diffusion Mixers (Tumble) with Intensifier/Agitator

c. Pneumatic Mixers

284
285
286 Although pneumatic mixers may differ from one another in vessel geometry, air
287 nozzle type, and air nozzle configuration, no pneumatic mixer subclasses have
288 been identified.
289
290

C. Granulation

1. Definitions

a. Unit Operations

291
292
293 Granulation: The process of creating granules. The powder morphology is
294 modified through the use of either a liquid that causes particles to bind through
295 capillary forces or dry compaction forces. The process will result in one or more
296 of the following powder properties: enhanced flow; increased compressibility;
297 densification; alteration of physical appearance to more spherical, uniform, or
298 larger particles; and/or enhanced hydrophilic surface properties.
299

b. Operating Principles

i. Dry Granulation

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- 310 Dry powder densification and/or agglomeration by direct
311 physical compaction.
- 312
- 313 ii. Wet High-Shear Granulation
- 314
- 315 Powder densification and/or agglomeration by the incorporation
316 of a granulation fluid into the powder with high-power-per-unit
317 mass, through rotating high-shear forces.
- 318
- 319 iii. Wet Low-Shear Granulation
- 320
- 321 Powder densification and/or agglomeration by the incorporation
322 of a granulation fluid into the powder with low-power-per-unit
323 mass, through rotating low-shear forces.
- 324
- 325 iv. Low-Shear Tumble Granulation
- 326
- 327 Powder densification and/or agglomeration by the incorporation
328 of a granulation fluid into the powder with low-power-per-unit
329 mass, through rotation of the container vessel and/or intensifier
330 bar.
- 331
- 332 v. Extrusion Granulation
- 333
- 334 Plasticization of solids or wetted mass of solids and
335 granulation fluid with linear shear through a sized orifice using
336 a pressure gradient.
- 337
- 338 vi. Rotary Granulation
- 339
- 340 Spheronization, agglomeration, and/or densification of a wetted or
341 non-wetted powder or extruded material. This is accomplished by
342 centrifugal or rotational forces from a central rotating disk, rotating
343 walls, or both. The process may include the incorporation and/or
344 drying of a granulation fluid.
- 345
- 346 vii. Fluid Bed Granulation
- 347
- 348 Powder densification and/or agglomeration with little or no shear
349 by direct granulation fluid atomization and impingement on
350 solids, while suspended by a controlled gas stream, with
351 simultaneous drying.
- 352
- 353 viii. Spray Dry Granulation
- 354

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355 A pumpable granulating liquid containing solids (in solution or
356 suspension) is atomized in a drying chamber and rapidly dried by a
357 controlled gas stream, producing a dry powder.

358
359 ix. Hot-melt Granulation

360
361 An agglomeration process that utilizes a molten liquid as a
362 binder(s) or granulation matrix in which the active
363 pharmaceutical ingredient (API) is mixed and then cooled down
364 followed by milling into powder. This is usually accomplished
365 in a temperature controlled jacketed high shear granulating tank
366 or using a heated nozzle that sprays the molten binders(s) onto
367 the fluidizing bed of the API and other inactive ingredients.

368
369 x. Melt Extrusion

370
371 A process that involves melting and mixing API and an excipient
372 (generally a polymer) using low or high shear kneading screws
373 followed by cooling and then milling into granules. Thermal
374 energy for melting is usually supplied by the electric/water heater
375 placed on the barrel. Materials are either premixed or fed into an
376 extruder separately. Melt extruder subclasses primarily are
377 distinguished by the configuration of the screw.

- 378
- 379 • Single screw extruder
- 380 • Twin screw extruder
- 381

2. *Equipment Classification*

382
383
384 a. Dry Granulator

385
386 Dry granulator subclasses primarily are distinguished by the densification force
387 application mechanism.

- 388
- 389 • Slugging
- 390 • Roller Compaction
- 391

392 b. Wet High-Shear Granulator

393
394 Wet high-shear granulator subclasses primarily are distinguished by the
395 geometric positioning of the primary impellers; impellers can be top, bottom,
396 or side driven.

- 397
- 398 • Vertical (Top or Bottom Driven)
- 399 • Horizontal (Side Driven)
- 400

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401 c. Wet Low-Shear Granulator

402

403 Wet low-shear granulator subclasses primarily are distinguished by the
404 geometry and design of the shear inducing components; shear can be induced
405 by rotating impeller, reciprocal kneading action, or convection screw action.

406

- 407 • Planetary
- 408 • Kneading
- 409 • Screw

410

411 d. Low-Shear Tumble Granulator

412

413 Although low-shear tumble granulators may differ from one another in vessel
414 geometry and type of dispersion or intensifier bar, no low-shear tumble
415 granulator subclasses have been identified.

416

- 417 • Slant cone
- 418 • Double cone
- 419 • V-blender

420

421 e. Extrusion Granulator

422

423 Extrusion granulator subclasses primarily are distinguished by the
424 orientation of extrusion surfaces and driving pressure production
425 mechanism.

426

- 427 • Radial or Basket
- 428 • Axial
- 429 • Ram
- 430 • Roller, Gear, or Pelletizer

431

432 f. Rotary Granulator

433

434 Rotary granulator subclasses primarily are distinguished by their structural
435 architecture. They have either open top architecture, such as a vertical centrifugal
436 spheronizer, or closed top architecture, such as a closed top fluid bed dryer.

437

- 438 • Open
- 439 • Closed

440

441 g. Fluid Bed Granulator

442

443 Although fluid bed granulators may differ from one another in geometry,
444 operating pressures, and other conditions, no fluid bed granulator subclasses
445 have been identified.

446

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447 h. Spray Dry Granulator

448
449 Although spray dry granulators may differ from one another in geometry,
450 operating pressures, and other conditions, no spray dry granulator subclasses have
451 been identified.

452
453 i. Hot-melt Granulator

454
455 Although, hot-melt granulator may differ from one another in primarily melting the
456 inactive ingredient (particularly the binder or other polymeric matrices), no
457 subclasses have been identified at this time.

458
459 Note:

460 If a single piece of equipment is capable of performing multiple discrete unit operations (mixing,
461 granulating, drying), the unit was evaluated solely for its ability to granulate. If multifunctional
462 units were incapable of discrete steps (fluid bed granulator/drier), the unit was evaluated as an
463 integrated unit.

464
465 **D. Drying**

466
467 *1. Definitions*

468
469 a. Unit Operation

470
471 Drying: The removal of a liquid from a solid by evaporation.

472
473 b. Operating Principles

474
475 i. Direct Heating, Static Solids Bed

476
477 Heat transfer is accomplished by direct contact between the wet
478 solids and hot gases. The vaporized liquid is carried away by the
479 drying gases. There is no relative motion among solid particles.
480 The solids bed exists as a dense bed, with the particles resting upon
481 one another.

482
483 ii. Direct Heating, Moving Solids Bed

484
485 Heat transfer is accomplished by direct contact between the wet
486 solids and hot gases. The vaporized liquid is carried away by the
487 drying gases. Solids motion is achieved by either mechanical
488 agitation or gravity force, which slightly expands the bed enough to
489 flow one particle over another.

490
491 iii. Direct Heating, Fluidized Solids Bed

492

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- 493 Heat transfer is accomplished by direct contact between the wet
494 solids and hot gases. The vaporized liquid is carried away by the
495 drying gases. The solids are in an expanded condition, with the
496 particles supported by drag forces caused by the gas phase. The
497 solids and gases intermix and behave like a boiling liquid. This
498 process commonly is referred to as fluid bed drying.
499
- 500 iv. Direct Heating, Dilute Solids Bed, Spray Drying
501
502 Heat transfer is accomplished by direct contact between a highly
503 dispersed liquid and hot gases. The feed liquid may be a solution,
504 slurry, emulsion, gel or paste, provided it is pumpable and capable
505 of being atomized. The fluid is dispersed as fine droplets into a
506 moving stream of hot gases, where they evaporate rapidly before
507 reaching the wall of the drying chamber. The vaporized liquid is
508 carried away by the drying gases. The solids are fully expanded
509 and so widely separated that they exert essentially no influence on
510 one another.
511
- 512 v. Direct Heating, Dilute Solids Bed, Flash Drying
513
514 Heat transfer is accomplished by direct contact between wet solids
515 and hot gases. The solid mass is suspended in a finely divided state
516 in a high-velocity and high-temperature gas stream. The vaporized
517 liquid is carried away by the drying gases.
518
- 519 vi. Indirect Conduction, Moving Solids Bed
520
521 Heat transfer to the wet solid is through a retaining wall. The
522 vaporized liquid is removed independently from the heating
523 medium. Solids motion is achieved by either mechanical agitation
524 or gravity force, which slightly expands the bed enough to flow one
525 particle over another.
526
- 527 vii. Indirect Conduction, Static Solids Bed
528
529 Heat transfer to the wet solid is through a retaining wall. The
530 vaporized liquid is removed independently from the heating
531 medium. There is no relative motion among solid particles. The
532 solids bed exists as a dense bed, with the particles resting upon one
533 another.
534
- 535 viii. Indirect Conduction, Lyophilization
536
537 Drying in which the water vapor sublimates from the product after
538 freezing.

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ix. Gas Stripping

Heat transfer is a combination of direct and indirect heating. The solids motion is achieved by agitation and the bed is partially fluidized.

x. Indirect Radiant, Moving Solids Bed

Heat transfer is accomplished with varying wavelengths of energy. Vaporized liquid is removed independently from the solids bed. The solids motion is achieved by mechanical agitation, which slightly expands the bed enough to flow one particle over one another. This process commonly is referred to as microwave drying.

2. Equipment Classifications

a. Direct Heating, Static Solids Bed

Static solids bed subclasses primarily are distinguished by the method of moving the solids into the dryer.

- Tray and Truck
- Belt

b. Direct Heating, Moving Solids Bed

Moving solids bed subclasses primarily are distinguished by the method or technology for moving the solids bed.

- Rotating Tray
- Horizontal Vibrating Conveyor

c. Direct Heating, Fluidized Solids Bed (Fluid Bed Dryer)

Although fluid bed dryers may differ from one another in geometry, operating pressures, and other conditions, no fluidized solids bed dryer subclasses have been identified.

d. Direct Heating, Dilute Solids Bed, Spray Dryer

Although spray dryers may differ from one another in geometry, operating pressures, and other conditions, no spray dryer subclasses have been identified.

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- 584 e. Direct Heating, Dilute Solids Bed, Flash Dryer
585
586 Although flash dryers may differ from one another in geometry, operating
587 pressures, and other conditions, no flash dryer subclasses have been identified.
588
- 589 f. Indirect Conduction Heating, Moving Solids Bed
590
591 Moving solids bed subclasses primarily are distinguished by the method or
592 technology for moving the solids bed.
593
- 594 • Paddle
 - 595 • Rotary (Tumble)
 - 596 • Agitation
- 597
- 598 g. Indirect Conduction Heating, Static Solids Beds
599
600 No indirect heating, static solids bed shelf dryer subclasses have been
601 identified.
602
- 603 h. Indirect Conduction, Lyophilization
604
605 No lyophilizer subclasses have been identified.
606
- 607 i. Gas Stripping
608
609 Although gas stripping dryers may differ from one another in geometry, shape of
610 agitator, and how fluidizing gas is moved through the bed, no gas stripping dryer
611 subclasses have been identified.
612
- 613 j. Indirect Radiant Heating, Moving Solids Bed (Microwave Dryer)
614
615 Although microwave dryers may differ from one another in vessel
616 geometry and the way microwaves are directed into the solids, no
617 indirect radiant heating, moving solids bed dryer subclasses have been
618 identified.
619

620 Note: If a single piece of equipment is capable of performing multiple discrete unit operations
621 (mixing, granulating, drying), the unit was evaluated solely for its ability to dry. The drying
622 equipment was sorted into similar classes of equipment, based upon the method of heat transfer
623 and the dynamics of the solids bed.
624

E. Unit Dosing

1. Definitions

a. Unit Operation

630

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631 Unit Dosing: The division of a powder blend into uniform single portions for
632 delivery to patients.

633
634 b. Operating Principles

635
636 i. Tableting

637
638 The division of a powder blend in which compression force is
639 applied to form a single unit dose.

640
641 ii. Encapsulating

642
643 The division of material into a hard gelatin capsule. Encapsulators
644 should all have the following operating principles in common:
645 rectification (orientation of the hard gelatin capsules), separation of
646 capsule caps from bodies, dosing of fill material/formulation,
647 rejoining of caps and bodies, and ejection of filled capsules.

648
649 iii. Powder Filling

650
651 The division of a powder blend into a container closure system.

652 2. *Equipment Classifications*

653
654 a. Tablet Press

655
656 Tablet press subclasses primarily are distinguished from one another by the
657 method that the powder blend is delivered to the die cavity. Tablet presses can
658 deliver powders without mechanical assistance (gravity), with mechanical
659 assistance (power assisted), by rotational forces (centrifugal), and in two different
660 locations where a tablet core is formed and subsequently an outer layer of coating
661 material is applied (compression coating).

- 662
663
 - Gravity
 - Power Assisted
 - Centrifugal
 - Compression Coating

664
665
666
667
668 Tablet press subclasses are also distinguished from one another for some special
669 types of tablets where more than one hopper and precise powder feeding
670 mechanism might be necessary.

- 671
672
 - Multi-tablet press for micro/mini tablet
 - Multi-layer tablet press (bi-layer, tri-layer)

673
674
675 b. Encapsulator

676

Contains Nonbinding Recommendations

677 Encapsulator subclasses primarily are distinguished from one another by the
678 method that is used for introducing material into the capsule. Encapsulators
679 can deliver materials with a rotating auger, vacuum, vibration of perforated
680 plate, tamping into a bored disk (dosing disk), or cylindrical tubes fitted with
681 pistons (dosator).

682

- 683 • Auger
- 684 • Vacuum
- 685 • Vibratory
- 686 • Dosing Disk
- 687 • Dosator

688

689 c. Powder Filler

690

691 Subclasses of powder fillers primarily are distinguished by the method used to
692 deliver the predetermined amount for container fill.

693

- 694 • Vacuum
- 695 • Auger

696

697 **F. Soft Gelatin Capsule**

698

699 *1. Definitions*

700

701 a. Unit Operations

702

703 i. Gel Mass Preparation: The manufacture of a homogeneous,
704 degassed liquid mass (solution) of gelatin, plasticizer, water, and
705 other additives, either in solution or suspension, such as colorants,
706 pigments, flavors, preservatives, etc., that comprise a unique
707 functional gel shell formation. The operation may be performed in
708 discreet steps or by continuous processing. Minor components can
709 be added after the liquid gel mass is made.

710

711 ii. Fill Mixing: The mixing of either liquids or solids with other liquids
712 to form a solution; blending of limited solubility solid(s) with a
713 liquid carrier and suspending agents used to stabilize the blend to
714 form a suspension; or the uniform combination of dry inert and drug
715 active substances to form a dry powder fill suitable for
716 encapsulation. The reader should refer to the other sections of this
717 document for dry fill manufacture.

718

719 iii. Encapsulation: The continuous casting of gel ribbons, with liquid
720 fill material being injected between the gel ribbons using a positive
721 displacement pump or, for dry materials being gravity or force fed
722 with capsule formation using a rotary die.

723

Contains Nonbinding Recommendations

- 724
725
726
727
728
729
- iv. Washing: The continuous removal of a lubricant material from the outside of the formed capsule. The washing operation is unique to each manufacturer's operation and generally uses in-house fabricated equipment. This equipment will not be discussed in this guidance document.
- 730
731
732
733
734
735
736
737
- v. Drying: The removal of the majority of water from the capsule's gel shell by tumbling and subsequent tray drying using conditioned air, which enhances the size, shape, and shell physical properties of the final product. The drying operation is unique to each manufacturer's operation and generally uses in-house fabricated equipment. This equipment will not be discussed in this guidance document.
- 738
739
740
741
- vi. Inspection/Sorting: The process wherein undesirable capsules are removed, including misshapen, leaking, and unfilled capsules as well as agglomerates of capsules.
- 742
743
744
- vii. Printing: The marking of a capsule surface for the purpose of product identification, using a suitable printing media or method.
- 745
- b. Operating Principles
- 746
- i. Mixing
- 747
748
749
750
751
752
753
754
- The combination of solid and liquid components, including suspending aid(s) at either ambient or elevated temperatures to form a solution, suspension, or dry powder blend for the manufacture of gel mass or fill material. Mixing also includes the incorporation of minor components into the liquid gel mass.
- 755
- ii. Deaggregation
- 756
757
758
759
760
761
- The removal of aggregates using a suitable homogenizer/mill to provide a pumpable fill material. The procedure has minimal effect on the particle size distribution of the initial solid component(s), and is viewed as a processing aid.⁹
- 762
- iii. Deaeration
- 763
764
765
766
767
768
- The removal of entrapped air from either the gel mass or fill material, solution or suspension. This process can take place in either the mixing vessel, through the application of vacuum, or a separate off-line step.

⁹ Carstensen, J. T., Theory of Pharmaceutical Systems, Volume 11 Heterogeneous Systems, Academic Press, New York, NY, 1973, p 51.

Contains Nonbinding Recommendations

- 769 iv. Holding
770
771 The storage of liquid gel mass or fill material in a vessel, with
772 a mixer or without, prior to encapsulation, which also may be
773 equipped with a jacket for either heating or cooling.
774
775 v. Encapsulation
776
777 The formation of capsules using a rotary die machine.¹⁰
778
779 vi. Inspection/Sorting
780
781 The physical removal of misshapen, leaking, or
782 agglomerated capsules, using either a manual or automatic
783 operation.
784
785 vii. Printing
786
787 The user of this document is asked to refer to the coating/printing
788 section, in which the use of various pieces of equipment are defined
789 and categorized.
790

2. Equipment Classifications

a. Mixers and Mixing Vessels

Mixer and mixing vessel subclasses primarily are distinguished by the mixing energy, mixer type, and whether a jacketed vessel with vacuum capabilities is used in conjunction with a specific mixer.

- Low Energy Mixer
- High Energy Mixer
- Planetary
- Jacketed Vessel With and Without Vacuum

b. Deaggregators

Deaggregator subclasses primarily are distinguished by the type of mechanical action imparted to the material.

- Rotor/Stator

¹⁰ Lachman, L., H. A. Lieberman, and J. L. Kanig (Eds.), *The Theory and Practice of Industrial Pharmacy*, Chapter 3, p. 359 (Stanley, J. P.), Philadelphia: Lea & Febiger, 1971; Tyle, P. (Ed.), *Specialized Drug Delivery Systems, Manufacturing and Production Technology*, Chapter 10, p. 409 (Wilkinson, P.K. and F.S. Hom), New York; M. Dekker, 1990; Porter, S., *Remington's Pharmaceutical Sciences*, Edition 18, Chapter 89, pp. 1662 - 1665, Easton, Penn.: Mack Publishing Co.

Contains Nonbinding Recommendations

- 810 • Roller
- 811 • Cutting Mills
- 812 • Stone Mills
- 813 • Tumbling Mills

814 815 c. Deaerators

816
817 Deaerator subclasses primarily are distinguished by the air removal path, either
818 through the bulk or through a thin film, and whether it is a batch or in-line
819 process.

- 820
- 821 • Vacuum Vessel
- 822 • Off Line/In Line

823 824 d. Holding Vessels

825
826 Although holding vessels may differ from one another, based upon whether they
827 are jacketed, with and without integrated mixing capabilities, no holding vessel
828 subclasses have been identified.

- 829
- 830 • Jacketed vessel with and without mixing system

831 832 e. Encapsulators

833
834 Encapsulator subclasses primarily are distinguished by the method used to inject
835 the fill material.

- 836
- 837 • Positive Displacement Pump
- 838 • Gravity or Force Fed

839 840 f. Inspection/Sorting

841
842 Inspection/sorting equipment subclasses primarily are distinguished by the
843 method used to present the capsule for viewing and mechanical method of
844 separation.

- 845
- 846 • Belt
- 847 • Vibratory
- 848 • Roller
- 849 • Rotary Table
- 850 • Electromechanical

851 852 **G. Coating/Printing/Drilling**

853 854 1. *Definitions*

855

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- 856 a. Unit Operation
- 857
- 858 i. Coating: The uniform deposition of a layer of material on
- 859 or around a solid dosage form, or component thereof, to:
- 860
- 861 a. Protect the drug from its surrounding environment
- 862 (air, moisture, and light), with a view to improving
- 863 stability.
- 864 b. Mask unpleasant taste, odor, or color of the drug.
- 865 c. Increase the ease of ingesting the product for the patient.
- 866 d. Impart a characteristic appearance to the tablets, which
- 867 facilitates product identification and aids patient
- 868 compliance.
- 869 e. Provide physical protection to facilitate handling. This
- 870 includes minimizing dust generation in subsequent unit
- 871 operations.
- 872 f. Reduce the risk of interaction between incompatible
- 873 components. This would be achieved by coating one or
- 874 more of the offending ingredients.
- 875 g. Modify the release of drug from the dosage form. This
- 876 includes delaying, extending, and sustaining drug substance
- 877 release.
- 878 h. Modify the dosage form by depositing the API or drug
- 879 substance on or around a core tablet, which could be a
- 880 placebo core tablet or a tablet containing another drug or a
- 881 fractional quantity of the same drug.
- 882
- 883 The coating material deposition typically is accomplished
- 884 through one of six major techniques:
- 885
- 886 a. Sugar Coating - Deposition of coating material onto
- 887 the substrate from aqueous solution/suspension of
- 888 coatings, based predominately upon sucrose as a raw
- 889 material.
- 890 b. Film Coating - The deposition of polymeric film onto
- 891 the solid dosage form.
- 892 c. Core Enrobing - The gelatin coating of gravity or force
- 893 fed pre- formed tablets or caplets.
- 894 d. Microencapsulation - The deposition of a coating material
- 895 onto a particle, pellet, granule, or bead core. The
- 896 substrate in this application ranges in size from submicron
- 897 to several millimeters. It is this size range that
- 898 differentiates it from the standard coating described in 1
- 899 and 2 above.
- 900 e. Compression Coating (also addressed in the Unit Dosing
- 901 section) - A coating process where a dry coatings blend is
- 902 applied on a previously compressed core tablet using a

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903 tablet compression machine.¹¹ Therefore, this process is
904 also known as a dry coating process that does not involve
905 any water or any other solvent in the coating process.

906 f. Active/API coating - Deposition of active pharmaceutical
907 ingredient (API or drug substance) on or around a core
908 tablet utilizing any of the above five coating techniques.

909
910 ii. Printing: The marking of a capsule or tablet surface for the
911 purpose of product identification. Printing may be accomplished
912 by either the application of a contrasting colored polymer (ink)
913 onto the surface of a capsule or tablet, or by the use of laser
914 etching.

915
916 The method of application, provided the ink formulation is not
917 altered, is of no consequence to the physical-chemical properties of
918 the product.

919
920 iii. Drilling: The drilling or ablating of a hole or holes through the
921 polymeric film coating shell on the surfaces of a solid oral dosage
922 form using a laser. The polymeric film shell is not soluble in
923 vivo. The hole or holes allow for the modified release of the drug
924 from the core of the dosage form.

b. Operating Principles

925
926
927
928 i. Pan Coating

929 The uniform deposition of coating material onto the surface of a
930 solid dosage form, or component thereof, while being translated via
931 a rotating vessel.

932
933 ii. Gas Suspension

934 The application of a coating material onto a solid dosage form, or
935 component thereof, while being entrained in a process gas stream.

936
937 Alternatively, this may be accomplished simultaneously by
938 spraying the coating material and substrate into a process gas
939 stream.

940
941
942 iii. Vacuum Film Coating
943

¹¹ W.C. Gunsel & R.G. Dusel. Compression-coated and layer tablets. In H.A.Lieberman, L. Lachman & B. Schwartz (Eds), *Pharmaceutical Dosage Forms: Tablets Vol 1*, 1989, pp. 247-249. MerceL Dekker, Inc.

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- 944 This technique uses a jacketed pan equipped with a baffle system.
945 Tablets are placed into the sealed pan, an inert gas (i.e., nitrogen)
946 is used to displace the air and then a vacuum is drawn.
947
- 948 iv. Dip Coating
949
950 Coating is applied to the substrate by dipping it into the
951 coating material. Drying is accomplished using pan coating
952 equipment.
953
- 954 v. Electrostatic Coating
955
956 A strong electrostatic charge is applied to the surface of the
957 substrate. The coating material containing oppositely charged ionic
958 species is sprayed onto the substrate.
959
- 960 vi. Compression Coating
961
962 Refer to the Unit Dosing section of this document.
- 963 vii. Ink-Based Printing
964
965 The application of contrasting colored polymer (ink) onto
966 the surface of a tablet or capsule.
967
- 968 viii. Laser Etching
969
970 The application of identifying markings onto the surface of a
971 tablet or capsule using laser-based technology.
972
- 973 ix. Drilling
974
975 A drilling system typically is a custom built unit consisting of a
976 material handling system to orient and hold the solid dosage form,
977 a laser (or lasers), and optics (lenses, mirrors, deflectors, etc.) to
978 ablate the hole or holes, and controls. The drilling unit may include
979 debris extraction and inspection systems as well. The sorting,
980 orienting, and holding equipment commonly is provided by dosage
981 form printing equipment manufacturers, and is considered ancillary
982 in this use.

2. Equipment Classification

a. Pan Coating

Pan coating subclasses primarily are distinguished by the pan configuration, the pan perforations, and/or the perforated device used to introduce process air for

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- 989 drying purposes. Perforated coating systems include both batch and continuous
990 coating processes.
991
- 992 • Non-perforated (conventional) Coating System
 - 993 • Perforated Coating System
- 994
- 995 b. Gas Suspension
- 996
- 997 Gas suspension subclasses primarily are distinguished by the method
998 by which the coating is applied to the substrate.
999
- 1000 • Fluidized Bed with bottom spray mechanism
 - 1001 • Fluidized Bed with tangential spray mechanism
 - 1002 • Fluidized Bed with top spray mechanism
 - 1003 • Fluidized Bed with Wurster column
 - 1004 • Spray Congealing/Drying
- 1005
- 1006 c. Vacuum Film Coating
- 1007
- 1008 Although there may be differences in the jacketed pan, baffle system, or
1009 vacuum source, no vacuum film coating subclasses have been identified.
1010
- 1011 d. Dip Coating
- 1012
- 1013 Because of the custom design associated with this class of coating, no dip
1014 coating subclasses or examples have been identified.
1015
- 1016 e. Electrostatic Coating
- 1017
- 1018 Because of the custom design associated with this class of coating, no
1019 electrostatic coating subclasses or examples have been identified.
1020
- 1021 f. Compression Coating
- 1022
- 1023 Refer to the Unit Dosing section of this document.
1024
- 1025 g. Ink-Based Printing
- 1026
- 1027 Ink-based printing subclasses primarily are distinguished by the method by which
1028 the marking is applied to a capsule or tablet surface.
1029
- 1030 • Offset
 - 1031 • Ink Jet
- 1032
- 1033 h. Laser Etching (Printing)
- 1034

Contains Nonbinding Recommendations

1035 Although laser etching systems may differ from one another, no laser
1036 etching subclasses have been identified.

1037
1038 i. Drilling

1039
1040 The method of producing the laser pulse that ablates the hole(s) is of no
1041 consequence to the physical-chemical properties of the product. Therefore, no
1042 dosage form drilling equipment subclasses have been identified.

1043
1044 **V. SUPAC-SS INFORMATION**

1045
1046 **A. Particle Size Reduction/Separation**

1047
1048 The same definition and classification applies as described in section IV. A. for IR/MR
1049 products.

1050
1051 **B. Mixing**

1052
1053 *1. Definitions*

1054
1055 a. Unit Operation

1056
1057 Mixing: The reorientation of particles relative to one another to achieve
1058 uniformity or randomness. This process can include wetting of solids by a liquid
1059 phase, dispersion of discrete particles, or deagglomeration into a continuous
1060 phase. Heating and cooling via indirect conduction may be used in this operation
1061 to facilitate phase mixing or stabilization.

1062
1063 b. Operating Principles

1064
1065 i. Convection Mixing, Low Shear: Mixing process with a repeated
1066 pattern of cycling material from top to bottom, in which dispersion
1067 occurs under low power per unit mass through rotating low shear
1068 forces.

1069
1070 ii. Convection Mixing, High Shear: Mixing process with a repeated
1071 pattern of cycling material from top to bottom, in which dispersion
1072 occurs under high power per unit mass through rotating high shear
1073 forces.

1074
1075 iii. Roller Mixing (Milling): Mixing process by high mechanical
1076 shearing action where compression stress is achieved by passing
1077 material between a series of rotating rolls. This is commonly
1078 referred to as compression or roller milling.

1079

Contains Nonbinding Recommendations

1080 iv. Static Mixing: Mixing process in which material passes through a
1081 tube with stationary baffles. The mixer is generally used in
1082 conjunction with an in-line pump.
1083

2. *Equipment Classification*

a. Convection Mixers, Low Shear

1084
1085
1086
1087 This group normally operates under low shear conditions and is broken down by
1088 impeller design and movement. Design can also include a jacketed vessel to
1089 facilitate heat transfer.
1090

- 1091 • Anchor or sweepgate
- 1092 • Impeller
- 1093 • Planetary
- 1094
- 1095

b. Convection Mixers, High Shear

1096
1097 This group normally operates only under high shear conditions. Subclasses are
1098 differentiated by how the high shear is introduced into the material, such as by a
1099 dispersator with serrated blades or homogenizer with rotor stator.
1100

- 1101 • Dispersator
- 1102 • Rotor stator
- 1103
- 1104

c. Roller Mixers (Mills)

1105
1106 No roller mixer subclasses have been identified.
1107

d. Static Mixers

1108
1109 No static mixer subclasses have been identified.
1110
1111

1112
1113
1114 Note: If a single piece of equipment is capable of performing multiple discrete unit operations,
1115 it has been evaluated solely for its ability to mix materials.
1116

C. Emulsification

1. *Definitions*

a. Unit Operation

1117
1118
1119
1120
1121
1122 Emulsification: The application of physical energy to a liquid system consisting of
1123 at least two immiscible phases, causing one phase to be dispersed into the other.
1124

b. Operating Principles

1125
1126
1127

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- 1128
1129
1130
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1132
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1141
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1143
1144
1145
1146
1147
1148
- i. Low Shear Emulsification: Use of low shear energy using mechanical mixing with an impeller to achieve a dispersion of the mixture. The effectiveness of this operation is especially dependent on proper formulation.
 - ii. High Shear Emulsification: Use of high shear energy to achieve a dispersion of the immiscible phases. High shear can be achieved by the following means:
 - a. Stirring the mixture with a high speed chopper or saw-tooth dispersator.
 - b. Passing the mixture through the gap between a high-speed rotor and a stationary stator.
 - c. Passing the mixture through a small orifice at high pressure (valve- type homogenizer) or through a small orifice at high pressure followed by impact against a hard surface or opposing stream (valve-impactor type homogenizer), causing sudden changes of pressure.

2. Equipment Classification

a. Low Shear Emulsifiers

1150
1151
1152
1153
1154
1155
1156

Although low shear emulsification equipment (mechanical stirrers or impellers) can differ in the type of fluid flow imparted to the mixture (axial-flow propeller or radial-flow turbines), no subclasses have been defined.

b. High Shear Emulsifiers

1157
1158
1159
1160
1161

Subclasses of high shear emulsification equipment differ in the method used to generate high shear.

- 1162
1163
1164
1165
- Dispersator
 - Rotor stator
 - Valve or pressure homogenizer

1166
1167
1168

Note: If a single piece of equipment is capable of performing multiple discrete unit operations, the unit has been evaluated solely for its ability to emulsify materials.

D. Deaeration

1. Definitions

a. Unit Operation

1170
1171
1172
1173
1174

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1175 Deaeration: The elimination of trapped gases to provide more accurate
1176 volumetric measurements and remove potentially reactive gases.
1177

1178 b. Operating Principles

1179
1180 The use of vacuum or negative pressure, alone or in combination with mechanical
1181 intervention or assistance.
1182

1183 2. *Equipment Classification*

1184 1185 a. Deaerators

1186
1187 Deaerator subclasses differ primarily in their air removal paths, either through the
1188 bulk material or through a thin film, and in whether they use a batch or in-line
1189 process.
1190

- 1191 • Off-Line or in-line
- 1192 • Vacuum vessel

1193
1194 Note: If a single piece of equipment is capable of performing multiple discrete unit operations,
1195 it has been evaluated solely for its ability to deaerate materials.
1196

1197 **E. Transfer**

1198 1. *Definition*

1200 a. Unit Operation

1201
1202 Transfer: The controlled movement or transfer of materials from one location to
1203 another.
1204
1205

1206 b. Operating Principles

- 1207
1208 i. Passive: The movement of materials across a non-mechanically-
1209 induced pressure gradient, usually through conduit or pipe.
1210
- 1211 ii. Active: The movement of materials across a mechanically-
1212 induced pressure gradient, usually through conduit or pipe.
1213

1214 2. *Equipment Classification*

1215 a. Low Shear

1216
1217 Active or passive material transfer, with a low degree of induced shear
1218
1219

- 1220 • Diaphragm
- 1221 • Gravity
- 1222 • Peristaltic
- 1223 • Piston
- 1224 • Pneumatic
- 1225 • Rotating lobe
- 1226 • Screw or helical screw

1227 1228 b. High Shear

1229

Contains Nonbinding Recommendations

1230 Active or mechanical material transfer with a high degree of induced shear

1231

1232 • Centrifugal or turbine

1233 • Piston

1234 • Rotating gear

1235

1236 Note: This section is intended to deal with the transfer of shear sensitive materials, including
1237 product or partially manufactured product. A single piece of equipment can be placed in either a
1238 low or high shear class, depending on its operating parameters. If a single piece of equipment is
1239 capable of performing multiple discrete unit operations, the unit has been evaluated solely for its
1240 ability to transfer materials.

1241

F. Packaging

1242

1243

1. Definitions

1244

1245

a. Unit Operation

1246

1247

1248 i. Holding: The process of storing product after completion of
1249 manufacturing process and prior to filling final primary packs.

1250

1251 ii. Transfer: The process of relocating bulk finished product from
1252 holding to filling equipment using pipe, hose, pumps and/or other
1253 associated components.

1254

1255 iii. Filling: The delivery of target weight or volume of bulk finished
1256 product to primary pack containers

1257

1258 iv. Sealing: A device or process for closing and/or sealing primary
1259 pack containers following the filling process.

1260

1261

b. Operating Principles

1262

1263 i. Holding: The storage of liquid, semi-solids, or product
1264 materials in a vessel that may or may not have temperature
1265 control and/or agitation.

1266

1267 ii. Transfer: The controlled movement or transfer of materials
1268 from one location to another.

1269

1270 iii. Filling: Filling operating principles involve several associated
1271 subprinciples. The primary package can be precleaned to remove
1272 particulates or other materials by the use of ionized air, vacuum,
1273 or inversion. A holding vessel equipped with an auger, gravity, or
1274 pressure material feeding system should be used. The vessel may
1275 or may not be able to control temperature and/or agitation. Actual
1276 filling of the dosage form into primary containers can involve a
1277 metering system based on an auger, gear, orifice, peristaltic, or
1278 piston pump. A head-space blanketing system can also be used.

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- 1279
1280 iv. Sealing: Primary packages can be sealed using a variety of
1281 methods, including conducted heat and electromagnetic
1282 (induction or microwave) or mechanical manipulation (crimping
1283 or torquing).

1284
1285 2. *Equipment Classification*

1286
1287 a. Holders

1288
1289 Although holding vessels can differ in their geometry and ability to control
1290 temperature or agitation, their primary differences are based on how materials
1291 are fed.

- 1292
1293 • Auger
1294 • Gravity
1295 • Pneumatic (nitrogen, air, etc.)

1296
1297 b. Fillers

1298
1299 The primary differences in filling equipment are based on how materials
1300 are metered.

- 1301
1302 • Auger
1303 • Gear pump
1304 • Orifice
1305 • Peristaltic pump
1306 • Piston

1307
1308 c. Sealers

1309
1310 The differences in primary container sealing are based on how energy is
1311 transferred or applied.

- 1312
1313 • Heat
1314 • Induction
1315 • Microwave
1316 • Mechanical or crimping
1317 • Torque

1318
1319